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# GANPAT UNIVERSITY B. TECH SEM. VII ELECTRONICS & COMMUNICATION ENGINEERING EXAMINATION NOV/DEC-2011 EC 705(A) EMBEDDED SYSTEMS

TIME: 3 HOURS

**TOTAL MARKS: 70** 

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### INSTRUCTIONS: Who bland on abordison automay minigate but modernich A

- 1. Attempt all questions.
- 2. Answers to the two sections must be written in separate answer books.
- 3. Figures to the right indicate full marks.
- 4. Assume suitable data, if necessary.

#### and excusioning cale against the SECTION-I

Que1	(A)	An analog input signal is given whose voltage range from 0 to 15V and an 8 bit digital encoding. Calculate the correct encoding of 6V.	5
	(B)	Elaborate the specialities of embedded systems.	4
	(C)	Elucidate serial communication of embedded system.	3
		A (A) Define task scheduling? D RO	
Que1	(A)	Explain the working of memory to read and write data in detail with net diagram.	4
	(B)	Discuss watchdog timer with the help of ATM machine.	4
	(C)	Enlist the applications of embedded systems.	4
Que2	(A)	Write a brief note on each: (1) OTP ROM (2) EPROM (3) Flash memory (4) PSRAM	8
	(B)	List out and explain different timer/counter structures.	3
	What.	1908 1 OR 1	
Que2	(A)	Explain controlling of DC motor using pulse width modulators.	3
	(B)	Write brief note on following building block:	8
	What	(1) CPU architecture (2) ADC & DAC (3) Display devices (4) Debug port	
Que3	(A)	Provide differences between CISC and RISC.	2
Que5	(B)	Explain real time embedded systems.	3
	(C)	List out and explain recent trends in embedded systems.	4
		Define and discuss memory write ability and storage permanence.	3

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#### **SECTION-II**

Que4	(A)	Define following terms: (1) Live lock (2) Semaphore (3) Multitasking (4) Thread (5)	5
	(B) (C)	Signal Define Arbitration, and explain various methods to handle the arbitration. Provide differences between monolithic kernel and micro kernel.  OR	5 2
Que4	(A)	Enlist the differences between Hard Real Time and Soft Real Time	3
(8)	(B)	Operating Systems.  Define the following terms:  (1) bit error (2) vectored interrupt (3) polling (4) firmware (5) ASIP	5
	(C)	(1) bit error (2) vectored interrupt (3) polling (4) firmware (5) ASIP Elaborate interrupt driven I/O using vectored interrupt, also summarize the flow of actions with diagrams.	4
Que5	(A)	Discuss the different types of preemptive scheduling algorithms. State the merits and demerits of each.	5
	(B)	What is a device driver? Explain its role in the OS context.	6
		(C) Elucidate serial communic SO concedded system.	
Que5	(A) (B)	Define task scheduling? Discuss various scheduling algorithms in detail.  Describe the strobe and handshaking control methods for data transfer in detail.	6 3
	(C)	What is task control block (TCB)? Explain the structure of TCB.	2
Que6	(A) (B)	Explain the priority inversion problem and explain how it can be solved?  Discuss the basic functions of real time kernel.	6

## **End of Paper**