

GANPAT UNIVERSITY
B. TECH SEM- IV (ELECTRICAL)
REGULAR EXAMINATION- APRIL-JUNE 2017
2EE401: Control System Engineering

Time: 3 Hrs

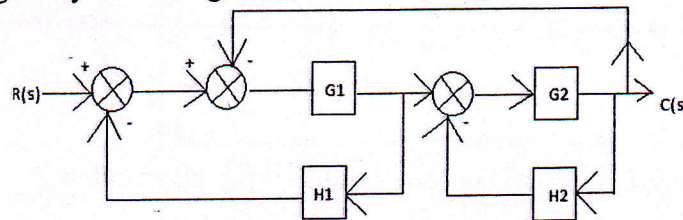
TOTAL MARKS: 60

Instructions: (1) This Question paper has two sections. Attempt each section in-separate answer book.
 (2) Figures on right indicate marks.
 (3) Be precise and to the point in answering the descriptive questions.

SECTION I

Q.1

- (A) Obtain the transfer function of the control system whose block diagram is shown [05] in below Figure by block diagram reduction technique.

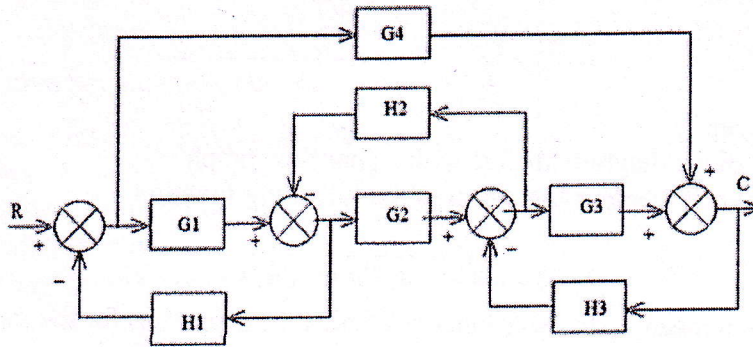


- (B) Explain force – voltage analogy in detail. [05]

OR

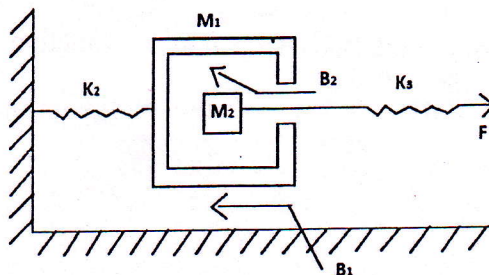
Q.1

- (A) Reduce the block diagram shown in fig. by using block diagram reduction technique [05]

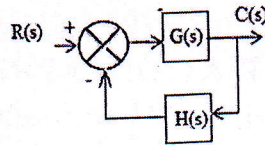


- (B) For the system shown in below Fig. [05]

- (i) Draw the mechanical network.
- (ii) Only draw force current analogous network.
- (iii) Only draw force voltage analogous network.



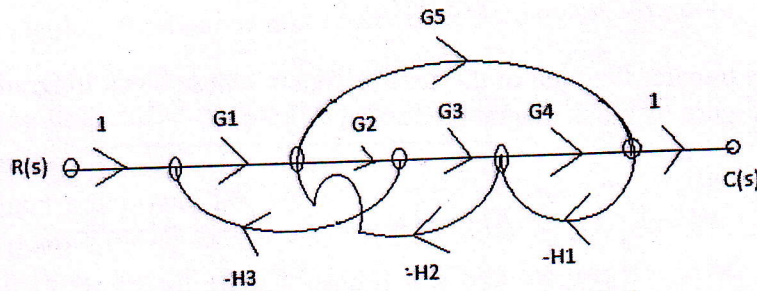
- Q.2 (A) Derive the transfer function of closed loop system showing in below Figure. [04]



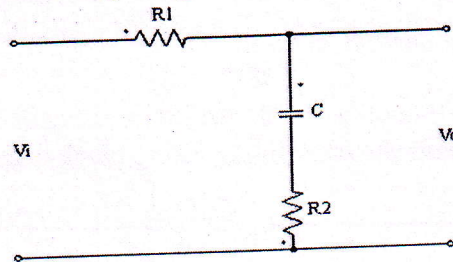
- (B) Explain Mason's gain formulae with suitable example and figure. [06]

OR

- Q.2 (A) The system signal flow graph is shown below. Find the transfer function of the system. [07]



- (B) Find the transfer function of lag compensator of fig. given below. [03]



Q.3 Attempt any three. [10]

- (A) Compare: Block diagram algebra with signal flow graph
 (B) Find the inverse Laplace transform of the following function

$$G(s) = \frac{4}{s(s^2 + 6s + 90)}$$

- (C) What do you mean by transfer function? Enlist the properties for the same.

SECTION II

- Q.4 (A) Apply Routh stability criterion and find the value of K for which the system is stable for given characteristics equation. $s^4 + 5s^3 + 5s^2 + 4s + K = 0$ [03]

- (B) Sketch the root locus for the open loop transfer function of a unity feedback control system given below, $K > 0$. [07]

$$G(s) = \frac{K}{s(s+3)(s+9)}$$

OR

Q.4

- (A) Check the stability of the following system using Routh criterion. [04]

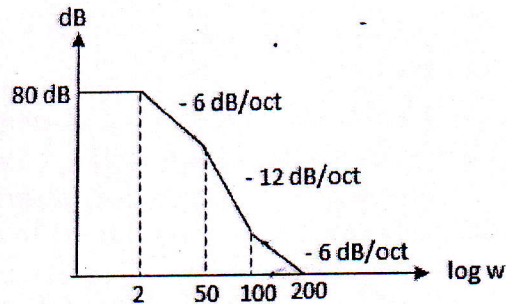
$$s^5 + s^4 + 4s^3 + 24s^2 + 3s + 63 = 0$$

- (B) Determine centroid, no of asymptotes, angle of asymptotes, and angle of departures for the unity feedback system shown below. [06]

$$G(s) = \frac{K}{s(s+2+3j)(s+2-3j)}, K > 0$$

Q.5

- (A) Recover the transfer function of the system from the figure shown below. Also obtain the value of system gain. [05]



- (B) Derive expressions of (i) Rise time, t_r (ii) Peak time, t_p and (iii) Peak overshoot, M_p for the system of above equation. [05]

$$\frac{C(s)}{R(s)} = \frac{\omega_n^2}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$

OR

Q.5

- (A) For the system having the open-loop transfer function [07]

$$G(s)H(s) = \frac{10}{s(s+1)(s+10)}$$

Determine the stability of the system by plotting the Bode Plot of the system.

- (B) Define following term. [03]
 (a) type of system (b) order of system (c) steady state error

Q.6

Attempt any three. [10]

- (A) Determine the value of K such that the roots of the characteristics equation given below lie to the left of line $s = -1$. $s^3 + 10s^2 + 18s + K = 0$

- (B) Using the Nyquist criterion determine the stability of the system whose open loop transfer function is given as

$$G(s)H(s) = \frac{50}{(s+1)(s+2)}$$

- (C) Discuss the designing steps of Phase lead-lag compensator.

END OF PAPER