GANPAT UNIVERSITY M. TECH SEM- II (ME-AMT) REGULAR EXAMINATION April - June 2015 3ME201 COMPUTER INTEGRATED MANUFACTURING

MAX. TIME: 3 HRS

MAX. MARKS: 60

Instructions: (1) This Question paper has two sections. Attempt each section in separate answer book.

- (2) Figures on right indicate marks.
- (3) Be precise and to the point in answering the descriptive questions.
- (4) Programming code (G and M codes) is given at the end of paper.

SECTION: I

Q.1

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A flexible manufacturing cell consists of three plus a load/unload stations. The load/unload (10) station is stations1 using two servers (material handling workers). Station 2 performs milling operations and consists of two server(two CNC milling machine). Station 3 performs vertical milling operations with three servers(three identical CNC vertical milling machine). Station 4 has two server that performs drilling (two CNC drill press). The three stations are connected by a part handling system that has three work carrier. The mean transport time is 3.5 min. The FMC produces four parts A, B, C and D, the part mix fractions are process routings for the three parts are presented in the table below. The operation frequency $F_{ijk} = 1.0$ for all operations. Determine: a) maximum production rate of the FMC, b) corresponding production rates of each product.

Part j	Part Mix Pj	Operation k	Description	Station i	Process	
			ROBSCEL	ANEOUS	Time t _{ijk} (min)	
A	0.2	1 an ine to	Load	1	4	
S. R. S.		2	Mill	2	15	
a statute		3	V.Mill	3	14	
		4	Drill	4	13	
		5	Unload	1	3	
В	0.3	1	Load	1	4	
		2	Drill	4	12	
		3	Mill	2	16	
r ochsper		4	V.Mill	3	,11 ₁₉	
		5.	Drill	4 months		
		6	Unload	1	3	
C	0.5	1	Load	1	4	
		2	Mill	2	10	
		3	Drill	4	9	
		4	Unload	1	3	
D	0.35	1	Load	1	4	
		2	V.Mili	3	18	
		3	Drill	4	8	
		4	Unload	1	3	

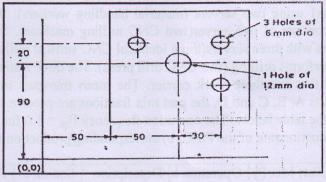
Suppose it is decided to increase the utilization of the two non-bottlenecks machining stations in the FMS by introducing a new past, part E, into the part mix. If the new product will be produced at a rate of 2 units/hr, what would be the ideal process routing (sequence and processing times) for part E that would increase the utilization of the two non-bottleneck machining stations to 100% each? The respective production rats of part A, B, C, and D will remain the same. Disregard the utilization of the load/unload station and the part handling system.

- Q.1 (A) Enlist the types of AS/RS and explain its application in manufacturing industries.
 - (B) Consider the following machine-component incidence matrix with 7 machines and 5 components. Obtain the final machine-component cells using Rank Order Clustering Algorithm.

HOLTTSAD!	RAMA A	Component						
		1	2	3	4	5		
	1	0	1	0	1	0		
	2	1	0	0	0	1		
Mashing	3	0	1	1	0	0		
Machine	4	1	0	0	0	1 -		
	5	0	0	1	1	0		
and and	6	0	0	0	0	1		
	7	0	1	1	1	0		

Q.2 (A) What are the various approaches available for CAPP?

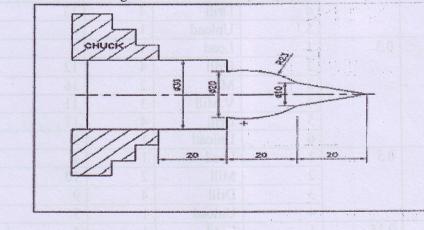
(B) Write a part program for PTP: Z level at 5 mm above the plate surface. And plate thickness = 10 mm. shown in fig.



OR

Q.2 (A) Enlist basic parts of robot & explain functionality of each part.

(B) Write a program of CNC Turning Centre for following component shown in fig Raw Material Size : 300 mm X 80 mm Long



Q.3 Attempt Any Two.

- (A) Enlist the FMS Elements and explain about FMS layout.
- (B) What is material handling? Explain about equipment's used for material handling.
- (C) Define manual part programming. What is meant by tool offset, tool length offset and cutter diameter compensation?

SECTION: II

Q.4 (A) Why Communication matrix required in CIM? Explain in detail Communication matrix.(B) Explain Open System Interconnection (OSI) in Brief and How it is differ from TCP/IP.

OR

Q.4 (A) Explain LAN concept its importance and different protocol and types.

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(10)

(10)

(10)

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(10)

- (B) Explain classification of Database manufacturing system and classification of DBMS.
- Q.5 (A) Draw CIM Wheel and explain strength and weakness of CIM Wheel.
 - (B) Explain the steps for implementing CIM in any organization.

OR

- Q.5 (A) What do you mean by CAD/CAM integration? Explain application integration.
 - (B) Describe fundamental communication concepts.

Q.6 Attempt Any Two.

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- (A) A text book is 600 pages long, Each page contains on average of 29 line, each line 9 words, If the word including blank space averages 6 characters, How much storage capacity required to store this book?.
- (B) Enlist Machine Control Unit in NC system.
- (c) What do you know about Preset tooling for NC turning machine? What are the various features to be taken care of while designing a CNC tool.

-----END OF PAPER-----

PREPARATORY FUNCTIONS (G CODES):

- G00 Rapid transverse positioning
- G01 Linear interpolation (federate movement)
- G02 Circular interpolation clockwise
- G03 Circular interpolation counterclockwise
- G04 Dwell
- G20 Inch data input (on some systems)
- G21 Metric data input (on some systems)
- G22 Salary zone programming
- G23 Cross through safety zone
- G27 Reference point return check
- G28 Return to reference point
- G29 Return from reference point
- G30 -Return to second reference point
- G40 Cutter diameter compensation cancel
- G41 Cutter diameter compensation left
- G42 Cutter diameter compensation right
- G43 Tool length compensation positive direction
- G44 Tool length compensation negative direction
- G49 Tool length compensation cancel
- G73 Peak drilling cycle
- G74 Counter tapping cycle
- G76 Fine boring cycle
- G80 Canned cycle cancel
- G81 Drilling cycle
- G83 Peak drilling cycle

- G87 Back boring cycle
- G90 Specifies absolute positioning
- G91 Specifies incremental positioning
- G92 Program absolute zero point

MISCELLANEOUS (M) FUNCTIONS:

- M00 Program stop
- M01 Optional stop
- M02 End of program (rewind tape)
- M03 Spindle start clockwise
- M04 Spindle start counterclockwise
- M05 Spindle stop
- M06 Tool change
- M08 Coolant on
- M09 Coolant off
- M13 Spindle on clockwise, coolant on (on some systems)

(10)

(10)

(10)

- M14 Spindle on counterclockwise, coolant on
- M17 Spindle and coolant off (on some systems)

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- M19 Spindle orient and stop
- M21 Mirror image X axis
- M22 Mirror image Y axis
- M23 Mirror image off
- M30 End of program, memory reset
- M41 Low range
- M42 High range 1 2 4 2 1 4 4 1
- M48 Override cancel off
- M49 Override cancel on
- M98 Jump to subroutine

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