

GANPAT UNIVERSITY
M. TECH. SEMESTER I ELECTRONICS & COMMUNICATION ENGINEERING
REGULAR EXAMINATION, JAN-2013

3EC102 SIGNAL DETECTION AND ESTIMATION

TOTAL Marks: 70

Time: 3 HOURS.

Instructions:

1. Attempt all questions.
2. Answers to the two sections must be written in separate answer books.
3. Figures to the right indicate full marks. Assume suitable data, if necessary.

SECTION-I

1. (A) Explain the Sufficient statistic. Consider the situation where the samples Y_1, Y_2, \dots, Y_K are independent random variables, each having a Bernoulli distribution with parameter p . Assume that the test statistic is $T(y) = \sum_{k=1}^K y_k$. Is $T(Y)$ a sufficient statistic? 5
 - (B) Consider the binary hypothesis problem with received conditional probabilities 7

$$f_{Y|H_0}(y|H_0) = \frac{1}{2(1-e^{-1})} e^{-|y|} \text{ for } |y| \leq 1 \quad \text{and}$$

$$f_{Y|H_1}(y|H_1) = \frac{1}{4} \text{rect}\left(\frac{y}{2}\right)$$

The hypotheses H_0 and H_1 are equally likely.

 - (a) Find the decision regions for which the probability of error is minimum.
 - (b) Calculate the minimum probability of error.
 - (c) Find the decision rule based on the Neyman-Pearson criterion, such that the probability of false alarm is constrained to be $PF = 0.5$.
- OR**
- 1 (A) Explain the detection of Known signals in with the Correction receiver for binary decision problem. 6
 - (B) Write a short note on signal detection application in binary symmetric channel. 6
 - 2 (A) In a digital communication system, consider a source whose output under hypothesis H_1 is a constant voltage of value m , while it's output under H_0 is zero. The received signal is corrupted by N , an AWGN of zero mean, and variance σ^2 . 6
 - (a) Set up the likelihood ratio test and determine the decision regions.
 - (b) Calculate the probability of false alarm and probability of detection.
 - (B) Explain MINIMAX Criterion With example. 5
- OR**
- 2 (A) Explain Optimum detection of M-ary signal in white Gaussian noise. 6
 - (B) Explain application of detection for Radar target model. 5
 - 3 (A) Obtain Optimum Decision Rule In Terms Of Likelihood Ratio And Threshold Using Bayes' Criterion. 6
 - (B) In digital communication system consider a source whose output under hypothesis H_1 is constant voltage of value m , while it's output under H_0 is zero. The received is corrupted by N , an AWGN. Suppose that the receiver takes K samples, Y_1, Y_2, \dots, Y_k . The noise samples are independent Gaussian random variables each with zero mean and variance σ^2 . obtain the optimum decision rule. 6

SECTION-II

- 4 (A) Explain the Multiple parameter estimation for random parameter. 6
 (B) Find \hat{x}_{ms} , the minimum mean-square error, and \hat{x}_{map} , the maximum a posteriori estimators, of X from the observation $Y = X + N$. X and N are random variables with density functions 6

$$f_X(x) = \frac{1}{2} \delta(x) + \frac{1}{2} \delta(x-1) \quad \text{and} \quad f_N(n) = \frac{1}{2} e^{-|n|} = \begin{cases} \frac{1}{2} e^n, & n \leq 0 \\ \frac{1}{2} e^{-n}, & n \geq 0 \end{cases}$$

OR

- 4 (A) Explain MLP Estimation in brief. 6
 (B) Consider K observations, such that 6
 $Y_k = m + N_k, k = 1, 2, \dots, K$
 Where m is unknown and N_k s are statistically independent zero mean Gaussian random variables with unknown variance σ^2 .
 (a) Find the estimates \hat{m} and $\hat{\sigma}^2$ for m and σ^2 , respectively.
 (b) Is \hat{m} an efficient estimator?
 (c) Find the conditional variance of the error $\text{var}[(\hat{m} - m) | m]$.
 5 (A) Explain cramer-rao Inequality for random parameter 6
 (B) ML Estimation for nonlinear estimation. 5

OR

- 5 (A) Explain baye's Estimation for random parameter. 8
 (B) Define types of estimation. 3
 6 (A) What is Estimation theory? with estimation model 6
 (B) MAP Estimation for linear estimation. 6

END OF PAPER